

Multivariable Math Theory

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Vectors

Coordinate Vectors

Proposition 1. *The set of vectors $\{\vec{e}_1, \dots, \vec{e}_n\}$ is a natural basis for $\mathbb{R}^n$.*

Let $n \in \mathbb{Z}^+$.

Let $\vec{v} = (v_1, v_2, \dots, v_n)$ be a vector in $\mathbb{R}^n$.

Then $\vec{v} = v_1\vec{e}_1 + v_2\vec{e}_2 + \dots + v_n\vec{e}_n$.

Proof. Since $\vec{v} = (v_1, v_2, \dots, v_n) \in \mathbb{R}^n$, then $v_1, v_2, \dots, v_n \in \mathbb{R}$.

Observe that

$$\begin{aligned} v_1\vec{e}_1 + v_2\vec{e}_2 + \dots + v_n\vec{e}_n &= v_1(1, 0, \dots, 0) + v_2(0, 1, \dots, 0) + \dots + v_n(0, 0, \dots, 1) \\ &= (v_1, 0, \dots, 0) + (0, v_2, \dots, 0) + \dots + (0, 0, \dots, v_n) \\ &= (v_1, v_2, \dots, v_n) \\ &= \vec{v}. \end{aligned}$$

Therefore, $\vec{v} = v_1\vec{e}_1 + v_2\vec{e}_2 + \dots + v_n\vec{e}_n$. □

Geometry of Vectors in $\mathbb{R}^2$ and $\mathbb{R}^3$